## 4 axis digitran bi-polar instrument motor drive MSE422C



#### control features

This 4 axis compact chopped constant current bi-polar drive conforms to the international extended 3U eurocard standard. It is ideally suited for use with the range of permanent magnet and 17HS series hybrid instrument motors together with the NEMA size 23 HS series hybrid stepper motors with current ratings up to 1.5 amps per phase. The ability to operate with rail voltages up to 30 Vdc provides excellent high speed performance with a choice of full step or half step phase control when improved low speed and mid range stability is achieved. The design which provides fully **independent control of 4 motors** on a single eurocard is therefore ideally suited for use in instrumentation and scientific apparatus requiring a multiple axis drive capability.

Matching motors to the **digitran** drive is simplified by the provision of a 4 position DIL switch to enable motor phase current to be set between 80 & 600 milli amps per phase. An external contact closure enables reduced current for operating the motor in a stationary condition thereby minimising motor temperature rise and system power consumption. Additionally, a 10 K Ohm potentiometer may be used to provide proportional control of motor current thereby providing the exact current setting required to suit the motor operating condition.

The units are controlled by clock pulses and direction signals which may either be CMOS compatible for maximum noise immunity or of the TTL open collector type.

A range of EM170 & PM 170 series 24Vdc power supply modules have been developed for use with the **MSE & PM422C digitran** drive providing a choice of power ratings sufficient for up to 24 motor axes, depending on the individual current setting for each motor.

PM 170 series power supplies are 19in x 3U high eurorack mounted units with sufficient space to fit either six **digitran** drives, providing drive for 24 motors, or an eight axis control system utilising two **digitran** PM422C drives & a PM381 based multiplexed 8 axis **digistep** controller. Control systems based on the PM422C drive therefore offer an excellent combination of performance in a compact rack mounting system.

# typical performance







Coils in series 0.6 amps per phase



### Current settings using MSE 422 drive

For each axis a 4 position DIL switch is provided to set up the drive parameters. These switches are positioned as shown below: Element 1 of each switch sets the step size while the remaining positions set the phase current. Alternatively, the phase current is set by an external potentiometer

#### on-board switch for current setting & step size



The above values are nominal

#### specification

Type without front panel Type with front panel			MSE 42 PM 42	2C 2C	note	S
motor supply	Vdc	10 - 30			Max ripple 3 V peak/peak @ pins 1a,1b & 2a.2b	
Max. input current	amps	4			depe	nding on output setting
ground			0 V		@ pins 31a,31b & 32a,32b	
dimensions						
height	mm		100		fits 3U high euro-rack	
width	mm	50			PM versions use 7E panel	
length	mm	220			international standard	
output stage		Chopped constant current				
phase control		Bi-polar				
output current per phase	amps	0.08 - 0.6				
number of drive axes		4				
phase current selection	method	on board DIL switches			alternative control via 10K	
		see above			potentiometer per axis	
Full step /.half step selection		on board DIL switches		see above		
external clock	CLOCK	'1' to '0' state signal		see chart below		
clockwise motor rotation	DIR	'1' state signal		see chart below		
counter clockwise rotation	DIR	'0' state signal		see chart below		
motor current off	MIOFF	ʻ0'st	ate signal or g	ground	see chart below	
20% standby current signal	PWRD	'0' state signal or ground		ground	see chart below	
external current control	XC 2	prop	portional to 10K		0-560 milli amps	
		pote	potentiometer wiper signal		see chart below	
potentiometer excitation	XC 1	outp	out reference for each axis		see chart below	
potentiometer connected	between	XC1	& 0v		see chart below	
motor connections	axis 1		axis 2	axis 3		axis 4
phase 1	pins 3a & 3	3b	7a & 7b	11a & 11b		15a & 15b
phase 1'	4a & 4b		8a & 8b	12a & 12b		16a & 16b
phase 2	5a & 5b		9a & 9b	13a & 13b		17a & 17b
phase 2'	6a & 6b		10a & 10b	14a & 14b		18a & 18b
control inputs						
CLOCK	19a		22a	25a		28a
DIR	19b		22b	25b		28b
PWRD	20a		23a	26a		29a
MIOFF	20b		23b	26b		29b
external current control						
XC1	21a		24a	27a		30a
XC2	21b		24b	27b		30b

